



SV2-005L2

Three-phase or single phase AC200 to 240V for 50W





*Please note that accessories depicted in the image are for illustrative purposes only and may not be included with the product.

Specifications

Model				SV2-005L2
General specifications	Capacity			50 W
	Input power supply	Voltage/ frequency	Main circuit	3-phase (or single phase) 200 to 240 VAC +10 to -15%, 50/60 Hz 270 to 324 VDC *1
			Control circuit	Single-phase 200 to 240 VAC +10 to -15%, 50/60 Hz 270 to 324 VDC *1
		Allowable frequency fluctuation	Main circuit/ control circuit	No more than ±5%
		Overvoltage category		III
	Control mode			Three-phase full-wave rectification, IGBT, PWM control, sine-wave current driving method
	Feedback			22-bit serial encoder (absolute) communication, fully closed control serial communication, analog feedback
	Operating environment	Operating atmosphere	Enclosure rating	IP20
			Pollution degree	Pollution degree: 2 (in an IP54 or higher control panel) However, usage under the following requirements required: • No corrosive gas or flammable gas present • No exposure to water, oil, or chemicals • No dust present
		Operating ambient temperature		-5 to +60°C 23 to 140°F (no freezing; reduced ratings at +55°C 131°F or more)
		Storage ambient temperature		-20 to +85°C -4 to +185°F (no freezing)
		Operating/storage ambient temperature		95% RH or less (no condensation)
		Altitude		2000 m 6561.7' or less above sea level (usable at reduced ratings at 1000 m 3280.8' or more)
		Vibration resistance		4.9 m/s ² 16.1'/s ² (JIS C60068-2-6 compliant)
		Impact resistance		19.6 m/s ² 64.3'/s ² (JIS C60068-2-27 compliant)
		Other		No static electricity noise, strong electric fields, magnetic fields, or radiation present
	Min. insulation	resistance		500 VDC, 1 M Ω or more with insulation resistance tester
	Applied standard	UL/CSA standards		UL61800-5-1, CSA22.2 No.274
		CE marking	Low-voltage directive	EN61800-5-1, EN50178
			EMI	EN55011 Class A, EN61800-3, EN61000-6-4
			EMS	EN61800-3, EN61000-6-2
		North America EMI standard		FCC Part15 B, ICES-003. Class A
	Structure	Туре		Attached to base mount
	Safety function			STO function (STO/EN61800-5-2)



	Safety function	Safety parameters		SIL3/EN61508, SIL CL 3/EN62061, PLe (Category3) / EN ISO13849-1: 2008
		Response time		8 ms (max.)
		Input		STO1, STO2: Base block signal for power module Internal impedance: $4.7~k\Omega$ Operable voltage range: $+24~V~\pm20\%$ Max. delay time: $8~ms$ (Time from turning STO1, STO2 off until motor current cutoff)
		Output		EDM: Built-in safety circuit status monitoring (fixed output) Max. allowable voltage: 30 VDC Max. allowable current: 50 mA DC Max. voltage drop at ON: 1.5 V Max. delay time: 8 ms (Time from changing STO1, STO2 until EDM change)
		Applied standard		EN61800-5-2, EN ISO13849-1: 2008, EN61508, EN62061, EN60204-1, EN61326-3-1
	Protection function			Overcurrent, overvoltage, undervoltage, overload, regenerative abnormalities, etc.
	Insulation withstand voltage			1500 VAC or more (between primary side and ground) 3000 VAC or more (between primary side and secondary side) 350 VAC: Between secondary circuit and ground
	Weight			Approx. 0.8 kg
Power supply/	Main circuit pow	er supply		Three-phase 200 V/Single phase 200 V
current capacity and	Max. applicable	motor capacity		50 W
power loss	Power supply ca	apacity for 1 ampl	ifier	Three-phase 200 V: 0.2 kVA, Single phase 200 V: 0.2 kVA
	Output current	Continuous		0.66 Arms
	·	Max.		2.1 Arms
	Main circuit pow	er loss		5.1 W
		sistor power loss		_
	Control circuit po			17 W
	Total power loss			22.1 W
	Rated input			Three-phase 200 V: 0.4 Arms, Single phase 200 V: 0.8 Arms
	current	Main circuit		0.2 Arms
		Control circuit		
	Rush current	Main circuit		34 A
D (Control circuit		4.5000 (1.14)
Performance specifications	Performance	Speed control ra	_	1:5000 (load torque ≤ rated torque conditions)
		Speed fluctuation rate	At load fluctuation	±0.01% or less with load fluctuations of 0 to 100% (at rated rotation speed)
			At main circuit voltage change	0% with ±10% of rated voltage (at rated rotation speed)
			At ambient temperature change	±0.1% or less with ambient temperatures of 0 to +50°C 32 to 122°F (at rated rotation speed)
		Torque control accuracy (reproducibility)		±1%
		Speed frequency response frequency		2.6 kHz
	Dynamic brake			Operated at main circuit power supply OFF, servo alarm, limit switch detection (LSP/LSN), forced stop detection (FSTOP)
	Regenerative resistor			Built-in regenerative resistor: 50 W to 400 W not installed 750 W to 5.0 kW installed External regenerative resistor: OP-84399 (50 W to 1.0 kW) OP-87073 (1.5 kW *2)
	Display Function	Panel function		7-segment LED Rotary switch ×2 (16 ch) Slide switch ×1 (4 ch)
		Status display L	ED	CHARGE: For notification of main circuit power supply input (orange) POWER: For notification of control circuit power supply input (green)



			CONNECT: For notification of connection (green) LINK1, LINK2: For notification of MECHATROLINK communication (green)
	Auxiliary function		Gain control, alarm history, Z-phase search, etc.
I/O		Number of inputs	7 (3 high-speed input, 4 general input)
specifications	signal	Max. input voltage	28.8 VDC
		Rated input voltage	24 VDC
		Min. ON voltage	19 VDC
		Min. OFF current/voltage	High-speed input: 0.6 mA, general input: 0.3 mA
		Common point mode	7 points/1 common point (1 terminal) (bidirectional)
		Input time constant	250 μs, 500 μs, 1 ms, 2.5 ms, 5 ms, 10 ms
		Input current	High-speed input: 4.5 mA, general input: 3.7 mA
		Input impedance	Approx. 4.7 kΩ
		Assignable input signals	Full signal assignment, logic-settable forced stop (FSTOP), external latch signals 1 to 3 (EXT1, EXT2, EXT3), origin return deceleration switch (DEC), forward limit switch (LSP), reverse limit switch (LSN), forward torque limit selection (PTL), reverse torque limit selection (NTL)
	Sequence	Number of outputs	4
	output signal	Output mode	Transistor NPN output
		Rated load	30 VDC / 50 mA
		Leakage current when OFF	0.1 mA
		Residual voltage when ON	1.5 VDC or less
		Common point mode	Independent common
		Assignable output signals	Individual signal assignment excluding ALARM signal, logic-settable alarm (ALARM), in position (INPOS), speed matching (VCMP), zero speed detection (ZSP), operation preparation complete (RDY), torque limiting (TLM), speed limiting (VLM), electromagnetic brake timing (BRAKE), warning (WARN), Positioning proximity (NEAR)
	Analog	Max. input voltage	±12 V
	Feedback Input signal monitor	Accuracy	±1% of F.S.
	signal monitor	Resolution	±10 bits
		Input impedance	30 kΩ
	Encoder division pulse output signal	Output mode	Phase A (A+/A-), phase B(B+/B-), phase Z (Z+/Z-): Differential line-driver output
		Line driver	SN75ALS174 (T.I.) or equivalent
		Output frequency	1.6 Mbps (with 2-phase, 4 times multiplication, 6.4 MHz or equivalent) *3
	Analog monitor	No. of channels	2 ch
	output	Output range	±10 V (linearity valid range ±8 V)
		Resolution	16 bits
		Conversion precision	±20 mV (typ.)
		Max. allowable load current	±10 mA
		Conversion speed	1.2 ms (typ.)
Communication	MECHATROLINGommunication protocol		MECHATROLINK-III
specifications	III communication	Station address	03H to EFH (Max. number of connectable slaves: 62)
		Transmission speed	100 Mbps
		Transmission frequency	125 μs, 250 μs, 500 μs, 750 μs, 1 to 4 ms (in multiples of 0.5 ms)
		Communication cycle	Support for values starting at transmission frequency × 1
		Number of transmitted bytes	32 bytes/station, 48 bytes/station (selectable with slide switch)
		Transmission media/cable	Category 5e-compliant, STP cross cable
		0 " " "	Desition control / and ad control / tourness control
		Operating specifications	Position control / speed control / torque control



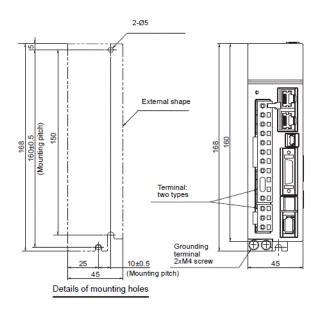
		(sequence, motion, monitor, adjustment, etc.)
	Max. transmission distance	50 m 164.0' *4
USB	Connected device	PC
communication	Communication standard	USB 2.0-compliant
	Function	Status display, parameter setting, tuning, etc.

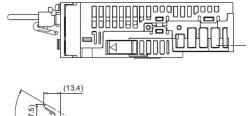
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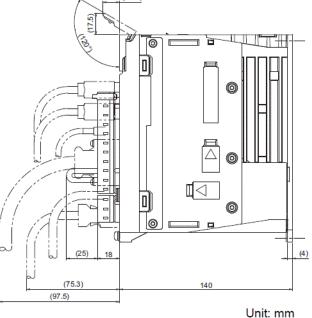
* Download CAD file or product manual for larger image/text and more detail.

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SV2-005L2 SV2-010L2 SV2-020L2







 $^{^{*1}}$ When using a DC power supply input, set "*AC/DC power supply" to "DC". *2 Use of 2 kW, 3 kW, and 5 kW servo amplifiers is possible depending on the operating conditions.

^{*3} The division ratio can be set arbitrarily with a parameter.

^{*4} For instances with 30 m 98.4' or more, use ferrite cores (OP-84409) with 2 turn-winding.